



Finding Bounds on Ehrhart Quasi-Polynomials

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Outline

1 Introduction

- What are (Ehrhart) quasi-polynomials?
- Where do they arise?
- Why do we need bounds on quasi-polynomials?

2 How do we find bounds?

- Continuous versus discrete domain extrema of polynomials
- Converting quasi-polynomials into polynomials

3 Conclusions and Future Work



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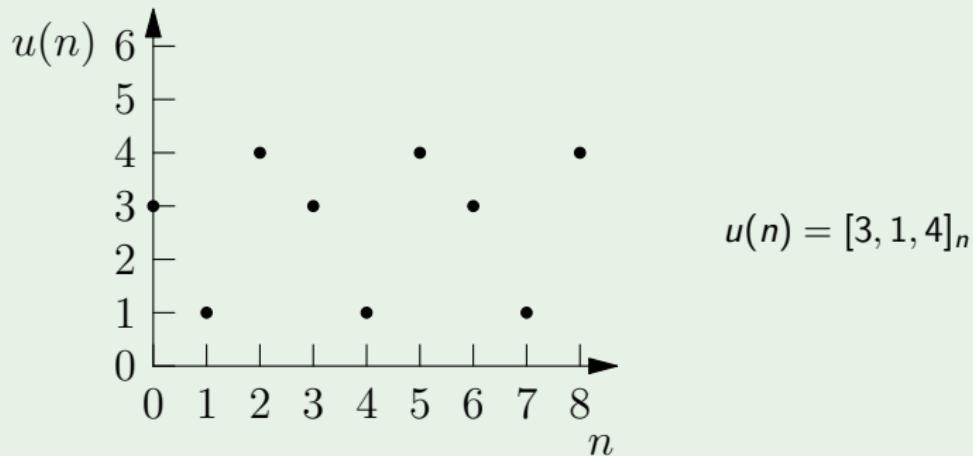
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Periodic Numbers

Example



Periodic Numbers

Definition

Let n be a discrete variable, i.e. $n \in \mathbb{Z}$. A 1-dimensional periodic number is a function that depends periodically on n .

$$u(n) = [u_0, u_1, \dots, u_{d-1}]_n = \begin{cases} u_0 & \text{if } n \equiv 0 \pmod{d} \\ u_1 & \text{if } n \equiv 1 \pmod{d} \\ \vdots & \\ u_{d-1} & \text{if } n \equiv d-1 \pmod{d} \end{cases}$$

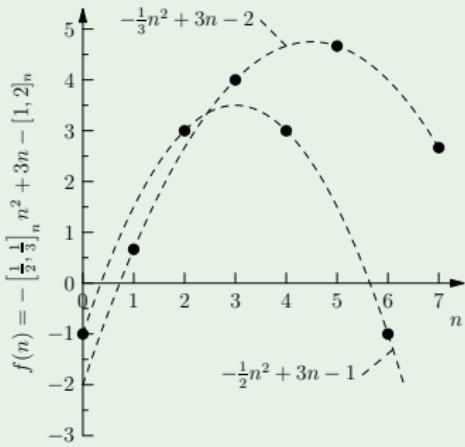
d is called the period.



Quasi-Polynomials

Example

$$\begin{aligned}f(n) &= -\left[\frac{1}{2}, \frac{1}{3}\right]_n n^2 + 3n - [1, 2]_n \\&= \begin{cases} -\frac{1}{3}n^2 + 3n - 2 & \text{if } n \equiv 0 \pmod{2} \\ -\frac{1}{2}n^2 + 3n - 1 & \text{if } n \equiv 1 \pmod{2} \end{cases}\end{aligned}$$



Quasi-Polynomials

Definition

A polynomial in a variable x is a linear combination of powers of x :

$$f(x) = \sum_{i=0}^g c_i x^i$$



Quasi-Polynomials

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Definition

A quasi-polynomial in a variable x is a polynomial expression with periodic numbers as coefficients:

$$f(n) = \sum_{i=0}^g u_i(n) n^i$$

with $u_i(n)$ periodic numbers.

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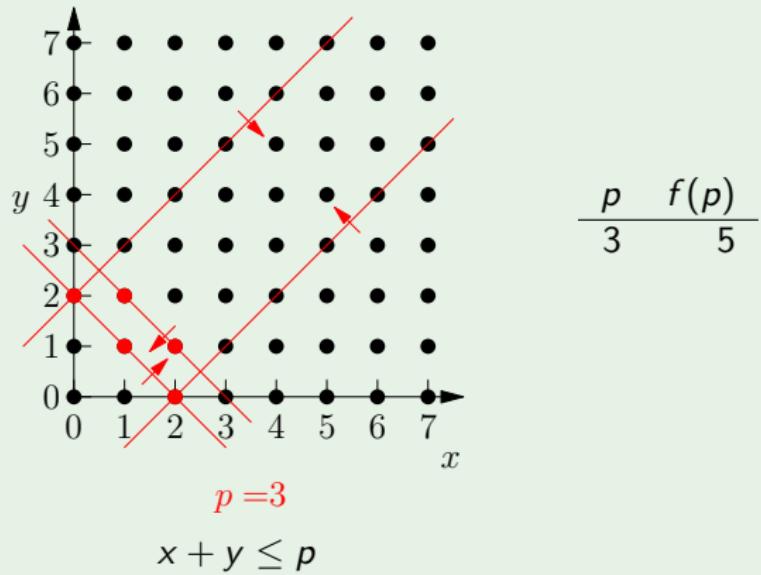
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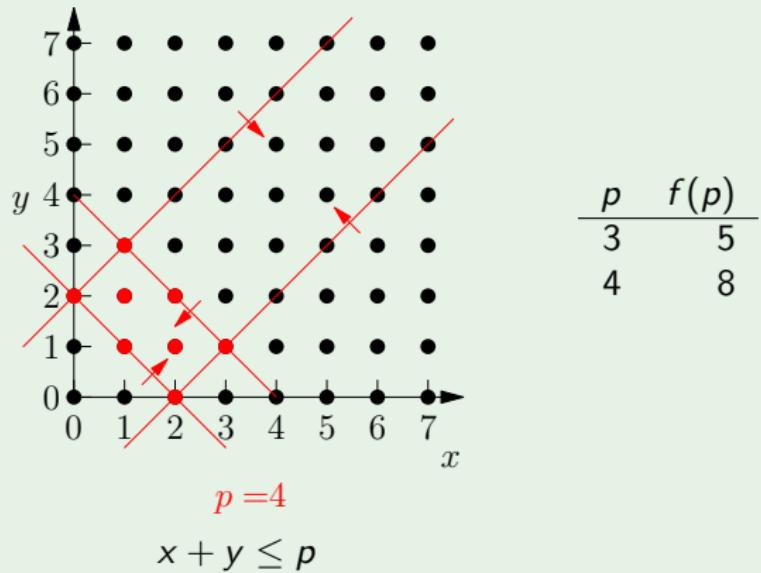
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Example



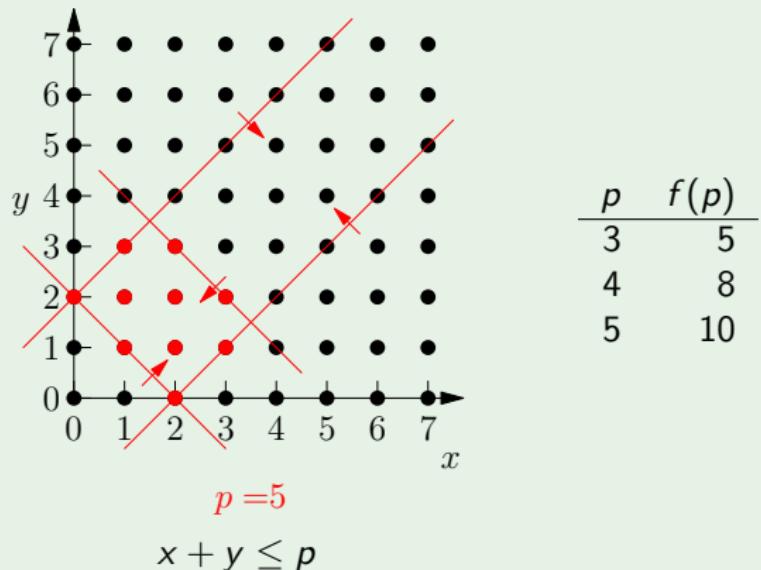
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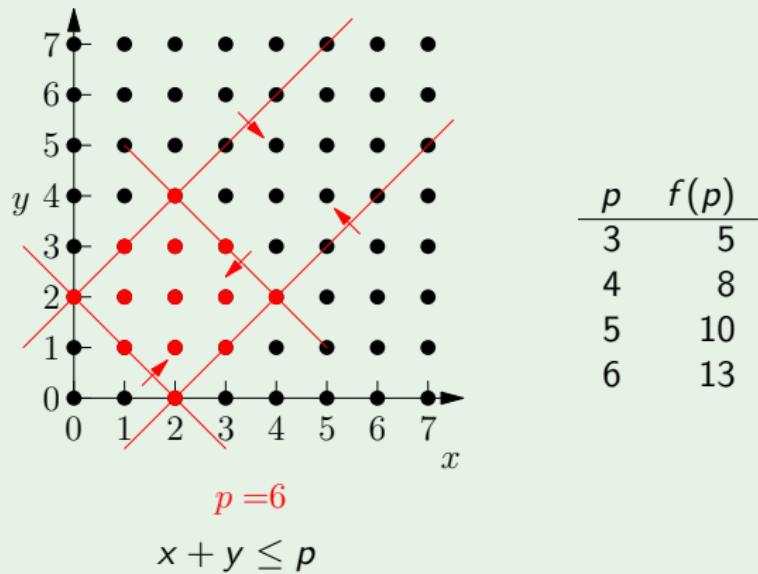
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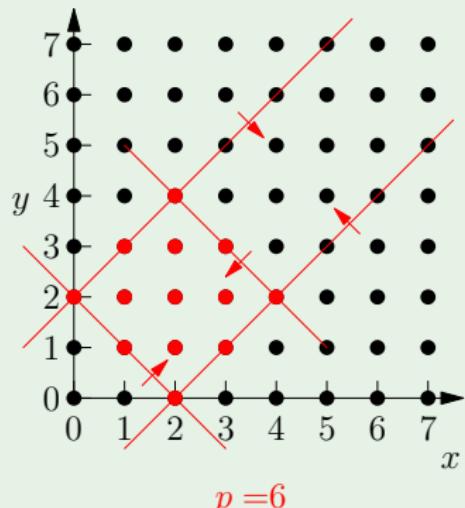
Where do Quasi-Polynomials arise?

Example



Where do Quasi-Polynomials arise?

Example



$$p = 6$$

$$x + y \leq p$$

p	$f(p)$
3	5
4	8
5	10
6	13

$$\frac{5}{2}p + \left[-2, \frac{-5}{2}\right]_p$$

Where do Quasi-Polynomials arise?

- The number of integer points in a **parametric polytope** P_p of dimension n is expressed as a piecewise quasi-polynomial of degree n in p (Clauss and Loehner).
- More general **polyhedral counting problems**:
Systems of linear inequalities combined with $\vee, \wedge, \neg, \forall$, or \exists (Presburger formulas).
- Many problems in **static program analysis** can be expressed as polyhedral counting problems.



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Why do we need bounds on quasi-polynomials?

Some problems in static program analysis need bounds on quasi-polynomials.

Example

Number of live elements = quasi-polynomial



Memory usage = maximum over all execution points



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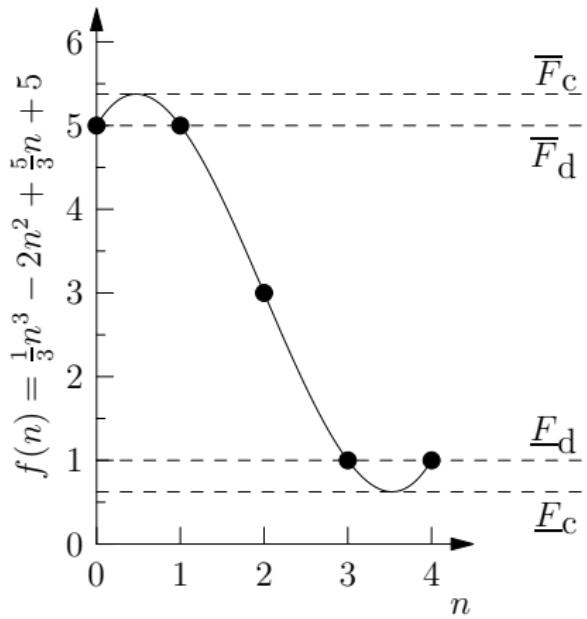
Continuous vs. Discrete domain extrema of polynomials

Discrete domain \Rightarrow evaluate in each point
Not possible for

- parametric domains
- large domains (NP-complete)



Continuous vs. Discrete domain extrema of polynomials



- The relative difference is smaller for
 - ▶ larger intervals
 - ▶ lower degree
- ⇒ Continuous-domain extrema can be used as approximation of discrete-domain extrema.

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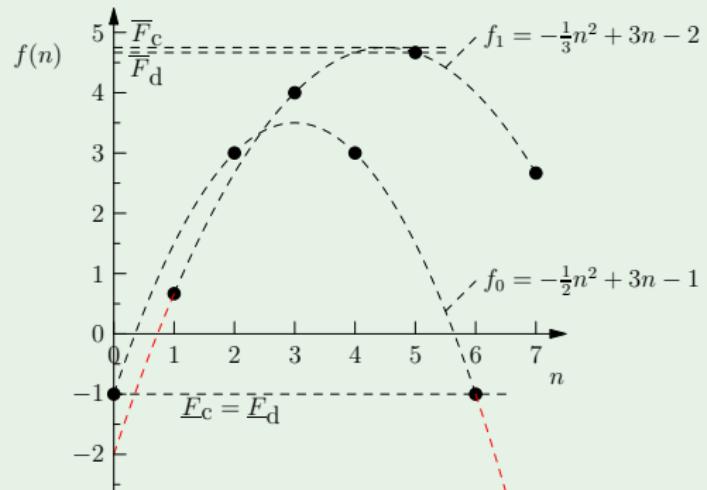
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How: Mod Classes

Example



Good for

- small period
- large domains

How: Other Methods

Other methods

- needed for large periods
 - offer trade-off between accuracy and computation time
 - see poster

Conclusions and Future Work

- Bounds on quasi-polynomials useful for static program analysis
 - Different methods fit different situations (period, degree, domain size).
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- Outlook
 - ▶ A hybrid method should be constructed.
 - ▶ Parametric bounds on parameterized quasi-polynomials

